

# Hilbert spaces and operators

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# Calculus 1

Definition. The determinant of a system of  $N$  vectors in  $\mathbb{R}^N$  is the signed volume of the associated parallelepiped

$$\det(V_1, \dots, V_N) = \pm \text{vol} \langle V_1, \dots, V_N \rangle$$

with the sign being  $+$  if you can pass from the standard basis of  $\mathbb{R}^N$  to the system of vectors in  $V$ , and being  $-$  otherwise.

Comment. This is the correct definition.

## Calculus 2

Definition. The integral of a continuous function  $f : [a, b] \rightarrow \mathbb{R}$  is the signed area below its graph. This can be computed as

$$\int_a^b f(x) dx = (b - a) \times \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N f(x_i)$$

where in order to compute the average height of the function, the points  $x_1, \dots, x_N \in [a, b]$  are chosen at random.

Comment. This is the best definition.

# Linear algebra 1

Definition. We say that  $M \in M_N(\mathbb{C})$  has eigenvector  $v \in \mathbb{C}^N$  with eigenvalue  $\lambda \in \mathbb{C}$  when  $M$  dilates by  $\lambda$  in the  $v$  direction:

$$Mv = \lambda v$$

When  $M$  has a basis of eigenvectors  $\{v_i\}$ , we call it diagonalizable, and we write  $M = PDP^{-1}$ , with  $D = \text{diag}(v_i)$ .

Examples. A diagonalizable matrix, and a non-diagonalizable one:

$$M = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad P = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

This follows indeed from  $M \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} y \\ x \end{pmatrix}$ , and from  $P \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} y \\ 0 \end{pmatrix}$ .

## Linear algebra 2

Theorem. The following happen:

- (1) The eigenvalues of  $M$  are the roots of  $f(x) = \det(M - x1_N)$ .
- (2) If we have  $N$  distinct eigenvalues,  $M$  is diagonalizable.
- (3) If  $M$  is normal,  $MM^* = M^*M$ , it is diagonalizable.
- (4) The diagonalizable matrices are dense inside  $M_N(\mathbb{C})$ .

Proof. The idea is as follows:

- (1) Follows from the eigenvalue equation,  $(M - \lambda 1_N)v = 0$ .
- (2) Vectors with different eigenvalues are linearly independent.
- (3) Generalizes “ $M \in M_N(\mathbb{R})$  symmetric  $\implies$  diagonalizable”.
- (4) Because the matrices with distinct eigenvalues are dense.

# Rotations 1

Definition. A scalar product  $\langle, \rangle$  on  $\mathbb{C}^N$  must satisfy:

- (1)  $\langle x, y \rangle$  is linear in  $x$ , antilinear in  $y$ .
- (2)  $\overline{\langle x, y \rangle} = \langle y, x \rangle$ , for any  $x, y$ .
- (3)  $\langle x, x \rangle \geq 0$ , for any  $x \neq 0$ .

Examples. The usual scalar product,  $\langle x, y \rangle = \sum_i x_i \bar{y}_i$ , that we can further complicate by adding weights, and so on.

Theorem. For a matrix  $U \in M_N(\mathbb{C})$ , the following are equivalent:

- (1)  $U$  preserves the scalar product,  $\langle Ux, Uy \rangle = \langle x, y \rangle$ .
- (2)  $U$  preserves the norm,  $\|Ux\| = \|x\|$ , where  $\|x\| = \sqrt{\langle x, x \rangle}$ .
- (3)  $U$  is unitary, in the sense that  $U^* = U^{-1}$ , where  $(U^*)_{ij} = \bar{U}_{ji}$ .

Proof. All this follows from  $\langle Mx, y \rangle = \langle x, M^*y \rangle$ .

## Rotations 2

Theorem 1. The unitaries in  $M_2(\mathbb{C})$  of determinant 1 are

$$U = \begin{pmatrix} a & b \\ -\bar{b} & \bar{a} \end{pmatrix}$$

with  $a, b \in \mathbb{C}$  satisfying  $|a|^2 + |b|^2 = 1$ .

Theorem 2. The unitaries in  $M_3(\mathbb{R})$  of determinant 1 are

$$U = \begin{pmatrix} x^2 + y^2 - z^2 - t^2 & 2(yz - xt) & 2(xz + yt) \\ 2(xt + yz) & x^2 + z^2 - y^2 - t^2 & 2(zt - xy) \\ 2(yt - xz) & 2(xy + zt) & x^2 + t^2 - y^2 - z^2 \end{pmatrix}$$

with  $x, y, z, t \in \mathbb{R}$  satisfying  $x^2 + y^2 + z^2 + t^2 = 1$ .

Proofs. 1 follows from  $U^* = U^{-1}$ , and 2 follows from 1.

# Hilbert spaces

Definition. A Hilbert space is a complex vector space  $H$ , typically infinite dimensional, with a scalar product  $\langle x, y \rangle$ , satisfying:

- (1)  $\langle x, y \rangle$  is linear in  $x$ , antilinear in  $y$ .
- (2)  $\overline{\langle x, y \rangle} = \langle y, x \rangle$ , for any  $x, y$ .
- (3)  $\langle x, x \rangle \geq 0$ , for any  $x \neq 0$ .
- (4)  $H$  is complete with respect to  $\|x\| = \sqrt{\langle x, x \rangle}$ .

Remark. Here (4) is based on Cauchy-Schwarz. Basic examples:

- (1)  $H = \mathbb{C}^N$ , with  $\langle x, y \rangle = \sum_i x_i \bar{y}_i$ .
- (2)  $H = l^2(\mathbb{N})$ , with  $\langle x, y \rangle = \sum_i x_i \bar{y}_i$ .
- (3)  $H = L^2(X)$ , with  $\langle f, g \rangle = \int_X f(x) \overline{g(x)} dx$ .



# Gram-Schmidt

Theorem. Any basis  $\{f_i\}_{i \in I}$ , in a dense sense, can be turned into an orthonormal basis  $\{e_i\}_{i \in I}$ , by using the Gram-Schmidt procedure.

Theorem. Any Hilbert space has an orthonormal basis  $\{e_i\}_{i \in I}$ . In other words, we have  $H \simeq l^2(I)$ , for some index set  $I$ .

Definition. When  $I$  is countable, and usually not finite,  $H$  is called separable. This is the same as saying that  $H \simeq l^2(\mathbb{N})$ .

Example. The space  $H = L^2[0, 1]$  is separable, because we can apply Gram-Schmidt to the basis  $f_i = x^i$ , with  $i \in \mathbb{N}$ .

# Linear operators

Theorem. Let  $H$  be a Hilbert space, with basis  $\{e_i\}_{i \in I}$ . We have

$$\mathcal{L}(H) \subset M_I(\mathbb{C})$$

with  $T : H \rightarrow H$  linear corresponding to the following matrix:

$$M_{ij} = \langle Te_j, e_i \rangle$$

- When  $\dim(H) = N < \infty$ , we obtain  $\mathcal{L}(H) \simeq M_N(\mathbb{C})$ .
- In the infinite separable case, we obtain  $\mathcal{L}(H) \subset M_\infty(\mathbb{C})$ .

Proof. The correspondence  $T \rightarrow M$  is indeed linear and injective.

Comment. However,  $H = L^2[0, 1]$  suggests not to use all this.

## Bounded operators

Theorem. Given a Hilbert space  $H$ , the linear operators  $T : H \rightarrow H$  which are bounded, in the sense that

$$\|T\| = \sup_{\|x\| \leq 1} \|Tx\|$$

is finite, form a complex algebra  $B(H)$ , which:

- (1) Is complete with respect to  $\|\cdot\|$  (Banach algebra).
- (2) Has an involution  $T \rightarrow T^*$ ,  $\langle Tx, y \rangle = \langle x, T^*y \rangle$ .

The norm and involution are related by  $\|TT^*\| = \|T\|^2$ .

Proof. Complex algebra is clear, given  $\{T_n\}$  Cauchy we can set  $Tx = \lim_{n \rightarrow \infty} T_n x$ , the involution comes from  $\varphi(x) = \langle Tx, y \rangle$  which is linear, and  $\|TT^*\| = \|T\|^2$  is by double inequality.

# Operator algebras

Definition. A  $C^*$ -algebra is an algebra  $A \subset B(H)$ , which:

(1) Is norm closed:  $T_n \in A, T_n \rightarrow T \implies T \in A$ .

(2) Is stable under the involution:  $T \in A \implies T^* \in A$ .

Definition. A von Neumann algebra is an algebra  $A \subset B(H)$ , which:

(1) Is weakly closed:  $T_n \in A, T_n x \rightarrow T x, \forall x \implies T \in A$ .

(2) Is stable under the involution:  $T \in A \implies T^* \in A$ .

Examples. We have  $C(X)$  and  $L^\infty(X)$ , acting by multiplication on  $L^2(X)$ . We will see that when  $T \in B(H)$  is normal, the algebras that it generates are of this form ("Spectral theorem").